# Livia Lestingi



♣ Personal Website
 ▲ Institutional Page ☑ livia.lestingi@polimi.it
 ★ Google Scholar ResearchGate
 in Linked-In livia\_lestingi livia.lestingi

## Education

Nov. 2019 – May 2023	Ph.D. in Information Technology (summa o	cum laude)	Politecnico di Milano	盦
	I obtained the Ph.D. title in <b>Computer Science and Engineering</b> at Politecnico di Milano (Depart- ment of Electronics, Information, and Bioengineering) in 2023. My research project focuses on the development of service robots applications involving hu- man-robot interaction in service settings. The work combines the reliability of formal verification techniques with untraditional models related to human behavior and physiology.			
Nov. 2017 - May 2019	Postgraduate Program	Politecnico di Milano Schoo	ol of Management, Cefriel	
	I have attended a two-year Postgraduate program (" <i>Master di I Livello</i> ") titled "Development of In- novative Software Products" while working as a Software Developer supported by special grant of Regione Lombardia. The program enrolls newly-hired professionals and helps them develop both their <b>technical</b> and <b>soft skills</b> . Technical courses cover topics related to up-to-date technologies and range from Web Development to Cloud Computing. Soft skills workshops deal topics such as Project Management and negotiation.			
Oct. 2014 - July 2017	<ul> <li>M.Sc. in Automation and Control Engineering (summa cum laude) POLITECNICO DI MILANO</li> <li>I obtained an M.Sc. in 2017 with a thesis titled "HRC-Team: A Model-driven Approach to Formal Verification and Deployment of Collaborative Robotic Applications." The M.Sc. thesis project has been carried out in collaboration with the Italian National Research Council (CNR). The project's context is the development of safer collaborative robotic applications for industrial settings. Politecnico di Milano has developed an innovative safety analysis methodology based on satisfiability checking of temporal logic formulae. The contributions of this thesis project are:         <ul> <li>a custom UML-based specification language for collaborative robotic application;</li> <li>a tool that processes the UML specification to generate the formal model compliant with the above-mentioned safety analysis methodology.</li> </ul> </li> </ul>			2

Sep. 2011 - Sep. 2014 B.Sc. in Automation Engineering

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### PUBLICATIONS

#### JOURNAL & MAGAZINE PUBLICATIONS

- L. Lestingi, D. Zerla, M. M. Bersani, M. Rossi. (2023). Specification, stochastic modeling and analysis of interactive service robotic applications. In Robotics and Autonomous Systems. doi:10.1016/j.robot.2023.104387.
- L. Lestingi, M. M. Bersani, M. Rossi. (2022). Model-Driven Development of Service Robot Applications Dealing with Uncertain Human Behavior. In IEEE Intelligent Systems. doi:10.1109/MIS.2022.3215698.
- L. Lestingi, M. Askarpour, M.M. Bersani, M. Rossi. (2021). A Deployment Framework for Formally Verified Human-Robot Interactions.. In IEEE Access. doi:10.1109/ACCESS.2021.3117852.
- M. Askarpour, L. Lestingi, S. Longoni, N. Iannacci, M. Rossi, F. Vicentini. (2021). Formallybased Model-Driven Development of Collaborative Robotic Applications. In Journal of Intelligent and Robotic Systems, 102(3), 1-26. doi:10.1007/S10846-021-01386-2.

#### **CONFERENCE PUBLICATIONS**

- 5. Bersani M.M., Camilli M., **Lestingi L.**, Mirandola R., Rossi M. (2023). *Explainable humanmachine teaming using model checking and interpretable machine learning*. Accepted for publication at Intl. Conf. on Formal Methods in Software Engineering (FormaliSE).
- Bersani M.M., Camilli M., Lestingi L., Mirandola R., Rossi M., Scandurra P. (2023). Towards better trust in human-machine teaming through explainable dependability. In IEEE 20th International Conference on Software Architecture Companion (ICSA-C) (pp. 86-90). doi:10.1109/ICSA-C57050.2023.00029.
- L. Lestingi, C. Sbrolli, P. Scarmozzino, G. Romeo, M.M. Bersani, and M. Rossi. (2022). Formal Modeling and Verification of Multi-Robot Interactive Scenarios in Service Settings. In International Conference on Formal Methods in Software Engineering (FormaliSE). doi:10.1145/3524482.3527653
- L. Lestingi, M. Askarpour, M.M. Bersani, M. Rossi. (2020). A Model-Driven Approach for the Formal Analysis of Human-Robot Interaction Scenarios. In Proceedings of 2020 IEEE International Conference on Systems, Man, and Cybernetics (SMC). doi:10.1109/SMC42975.2020.9283204.
- L. Lestingi, M. Askarpour, M.M. Bersani, M. Rossi. (2020). Formal Verification of Human-Robot Interaction in Healthcare Scenarios. In Proceedings of 18<sup>th</sup> International Conference on Software Engineering and Formal Methods (SEFM). doi:10.1007/978-3-030-58768-0.
- M. Askarpour, L. Lestingi, F. Buran, M. Rossi, F. Vicentini. (2020). Model-driven Risk Analysis for the Design of Safe Collaborative Robotic Applications. In Proceedings of 2020 IEEE International Conference on Human-Machine Systems (ICHMS). doi:10.1109/ICHMS49158.2020.9209450.

#### WORKSHOP PUBLICATIONS

- L. Lestingi (2021). Teaching Formal Methods to Software Engineers through Collaborative Learning (Short Paper). Formal Methods Teaching Workshop. Springer, Cham. doi:10.1007/978-3-030-91550-66
- L. Lestingi, M. Askarpour, M.M. Bersani, M. Rossi. (2020). Statistical Model Checking of Human-Robot Interaction Scenarios. In Proceedings of 1<sup>st</sup> Workshop on Agents and Robots for Reliable Engineered Autonomy (AREA20). doi:arxiv.org/abs/2007.11738.

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	Awards	<u> 0</u>			
2021	<b>Best Presentation Award</b> @ Doctoral Symposium held in conjuction with the 24th International Symposium on Formal Methods (FM 2021)				
	Service	*			
Organizer	Conferences				
	• Virtualization Chair @ International Conferences on Formal Methods in Software Engineering (FormaliSE'22)				
PC Member	Conferences				
	<ul> <li>Verification, Validation, and Testing Track @ International Conference on the Quality of Information and Communications Technology (QUATIC 2023)</li> </ul>				
	<ul> <li>Artifact Evaluation Committee Member @ International Conferences on Formal Methods in Software Engineering (FormaliSE'23)</li> </ul>				
	Workshops				
	• Workshop on Agents and Robots for reliable Engin	eered Autonomy (AREA 2022, 2023)			
Reviewer	Journals				
	Science of Computer Programming				
	Conferences				
	• Subreviewer @ International Conference on Computer Safety, Reliability and Security (Safecomp 2023, 2022, 2020)				
Speaker	Workshops				
L	<ul> <li>Presentation Title: "Model-driven development of formally verified hun Italian Workshop on Embedded Systems (IWES 2021)</li> </ul>				
	Teaching Experience	<u>.</u>			
Feb 2023 - June 2023	<b>Software Engineering (for Automation)</b> Teaching Assistant for Automation and Control Engineering M	Politecnico di Milano .Sc. students.			
Apr 2020 - June 2023	Formal Methods for Concurrent and Real-Time Systems	Politecnico di Milano			
1 5 /	Teaching Assistant for Computer Science and Engineering M.Sc				
Mar 2020 - June 2023	Fondamenti di Informatica POLITECNICO DI MILAN Teaching Assistant for Biomedical Engineering B.Sc. students (formerly "Informatica e Elementi di Informatica Medica") .				
Oct 2020 - Dec 2022	<b>Software Engineering Methodologies for Security</b> Teaching Assistant for Cyber Risk Strategy and Governance M.	Politecnico di Milano/UniBocconi Sc. students.			
Dec 2021 - Jan 2022	Basic Programming Techniques for AI and ML	Fondazione ITS INCOM			
Dec 2020 - Sep 2022	Advanced Programming Techniques in Python	Cefriel@Fastweb Digital Academy			
Nov 2020 - Jan 2023	Basic Programming in Python	Cefriel@Fastweb Digital Academy			

	Work Experience			
May 2023 -	Postdoctoral Researcher	Politecnico di Milano		
	The research aims at developing techniques for the analysis of industrial and robotic systems, starting from formal models learned automatically from field data.			
Nov. 2018 - Oct. 2019	Front-End Developer	Tinvention S.r.l @ UniCredit Services		
	As a front-end developer, I took part in re-designing a tool for internal use to the client's credit-risk section.			
Jan. 2018 - Oct. 2018	Big Data Developer	Tinvention S.r.l @ Data Reply IT		
	I was part of a Big Data Development team working for a primary firm in the mass distribution field. Th project involved the re-design of batch processes handling data related to stock and sales monitoring.			
Dec. 2017 - Oct. 2019	Full-Stack Developer	TINVENTION S.R.L.		
	My main job responsibility involved full-stack development for projects targeting clients' requirements.			
Oct. 2017 - Nov. 2017	Full-Stack Development Intern	TINVENTION S.R.L.		
	The internship's goal was to rapidly train the candidate on full-s management systems to front-end development.	tack development technologies, from database		

Skills

BACK-END DEVELOPMENT	
• Python; • C; • Java, JEE, JUnit; • REST WS, SOAP WS; • LUA; • Spring.	
Formal Methods	Xı
• Uppaal, Uppaal SMC; • zot; • Stochastic Hybrid Automata; • PCTL, MITL; • TRIO.	
Control Systems and Robotics	Ē
• ROS; • CoppeliaSim (formerly V-Rep); • Matlab, Simulink.	
Front-End Development	JS
• Angular • JavaScript, TypeScript; • HTML, CSS; • Bootstrap, Material Design.	
Development Support Tools	♦
• Maven, SBT; • GIT, SVN.	
Big Data Technologies	
• Scala; • Apache Spark; • Apache Kafka, Apache Oozie; • HBase.	
Languages	

## ITALIAN

• Mother tongue.

## English

- Spoken: Excellent, Written: Excellent;
- CAE Certification (Dec 2010), Level C1

Autorizzo al trattamento dati ai sensi del GDPR 2016/679 del 27 aprile 2016 (Regolamento Europeo relativo alla protezione delle persone fisiche per quanto riguarda il trattamento dei dati personali). Autorizzo la pubblicazione sul sito istituzione del Politecnico di Milano (sez. Amministrazione Trasparente) in ottemperanza al D. Lgs n. 33 del 14 marzo 2013 (e s.m.i.).